

LIST 4. Systems of Differential Linear Equations with Constant Coefficients.

Task 1. Solve the systems $\vec{x}' = A\vec{x}$ of the differential homogenous linear equations with constant coefficients:

(i) 2nd - dimension

$$\begin{array}{llll} \text{a. } A = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}; & \text{b. } A = \begin{bmatrix} 1 & -5 \\ 2 & -1 \end{bmatrix}; & \text{c. } A = \begin{bmatrix} 4 & -5 \\ 1 & 0 \end{bmatrix}; & \text{d. } A = \begin{bmatrix} -3 & -4 \\ -2 & -5 \end{bmatrix}; \\ \text{e. } A = \begin{bmatrix} 1 & 5 \\ -1 & -3 \end{bmatrix}; & \text{f. } A = \begin{bmatrix} -3 & -1 \\ 1 & -5 \end{bmatrix}; & \text{g. } A = \begin{bmatrix} 1 & -5 \\ -1 & -3 \end{bmatrix}; & \text{h. } A = \begin{bmatrix} -1 & 8 \\ 1 & 1 \end{bmatrix}; \\ \text{i. } A = \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix}; & \text{j. } A = \begin{bmatrix} -7 & 1 \\ -2 & -5 \end{bmatrix}; & & \\ \text{k. } A = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} & & & \end{array}$$

(ii) 3rd - dimension

$$\begin{array}{lll} \text{a. } A = \begin{bmatrix} 3 & -1 & 1 \\ -1 & 5 & -1 \\ 1 & -1 & 3 \end{bmatrix}; & \text{b. } A = \begin{bmatrix} 0 & 8 & 0 \\ 0 & 0 & -2 \\ 2 & 8 & -2 \end{bmatrix}; & \text{c. } A = \begin{bmatrix} 2 & -1 & 1 \\ 1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}; \\ \text{d. } A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix}; & \text{e. } A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}; & \text{f. } A = \begin{bmatrix} 2 & 1 & 2 \\ -1 & 0 & 0 \\ 1 & 1 & -1 \end{bmatrix}. \end{array}$$

Task 2. Solve the systems $\vec{x}' = A\vec{x} + \vec{h}(t)$ of the differential non-homogenous linear equations with constant coefficients:

(i) 2nd - dimension

$$\begin{array}{ll} \text{a. } A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} t \\ -t \end{bmatrix}; & \text{b. } A = \begin{bmatrix} -2 & -4 \\ -1 & 1 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} 1+4t \\ \frac{3}{2}t^2 \end{bmatrix}; \\ \text{c. } A = \begin{bmatrix} 1 & -2 \\ 1 & 4 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} e^t \\ e^{2t} \end{bmatrix}; & \text{d. } A = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} 0 \\ -5\sin t \end{bmatrix}; \\ \text{e. } A = \begin{bmatrix} 4 & -5 \\ 1 & -2 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} 4t-1 \\ t \end{bmatrix}; & \text{f. } A = \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} -\cos t \\ \cos t \end{bmatrix}; \\ \text{g. } A = \begin{bmatrix} -5 & -1 \\ 1 & -3 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} e^t \\ e^{2t} \end{bmatrix}; & \text{h. } A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} \cos t \\ 1 \end{bmatrix}. \end{array}$$

(ii) 3rd - dimension

$$A = \begin{bmatrix} 2 & 1 & -2 \\ -1 & 0 & 0 \\ 1 & 1 & -1 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} 2-t \\ 1 \\ 1-t \end{bmatrix}; \quad \text{b. } A = \begin{bmatrix} -1 & -2 & 0 \\ 0 & -1 & -1 \\ 0 & 0 & -1 \end{bmatrix}, \quad \vec{h}(t) = \begin{bmatrix} 2e^{-2t} \\ 1 \\ 1 \end{bmatrix}.$$